



In contrast to the conventional time-based ultrasound flow meter methods, which employ the inclined ultrasound beams to the pipe axis, the probe beam is emitted and propagates perpendicularly to the axis of the pipe. Ultrasound beam that reached to the opposed side of the transmitter was diverged and was also shifted due to the convection of the fluid flow passing through the test section. Therefore, the intensity profile of the received beam is moved to the downward of mean flow and the degree of the displacement is proportional to the flow rate.

The magnitude of the shift of the acoustic intensity distribution,  $S$ , can be obtained by the following equation.

$$S = \int_0^D \frac{u}{c} dy \quad (2)$$

Where  $c$  denotes the sound velocity, representative value of  $c$  is equal to 340 m/s for the air at room temperature and atmospheric pressure, and 1480 m/s for water.  $D$  denotes the internal diameter of the pipe,  $u = u(y, z)$  is the radial velocity distribution of the flow. For the air flow measurement with the pipe diameter of 160 mm, the magnitude of the shift is a few mm. When the velocity distribution in the test section is assumed to be axisymmetric, the flow rate could be directly obtained by using Abel transform of the amount of the shift. If the flow is distorted due to the bend, elbow, bulb or any kind of the disturbing element in the flow systems, the single path methodology could not be applied or suffered from the terrible measurement error. Since the secondary flow and backward flow after the aforementioned elements generates the distorted velocity profile, it becomes difficult to assume the symmetric velocity profile, i.e., the error will significantly be increased depending on the orientation of the probe beam. In contrast, the multi-path ultrasound shift method have the possibility to reflect the velocity modulation and is effective in reducing the bias error and in improving the accuracy of the resultant flow rate. In our previous works, quad ultrasound shift method at the radial alignments were proposed and applied to the distorted flow after the single 90 deg L-bend section. The investigation resulted that the oversampling effect at the intersection of radial beams causes the bias error of the measured flow rate. In the present study, the parallel beam alignment was employed. By integrating the spatial distribution of shift,  $S$ , the flow rate could be obtained by the following equation.

$$Qv = c \int_0^D S(z) dz \quad (3)$$

To calculate the flow rate on the basis of Eqn. 3, infinite number of shift values are required. As the distortion of velocity distribution in a pipe flow is not drastic, the distribution of the shift could be approximated by using the lower order polynomials. The order is limited by the number of measured shift values.

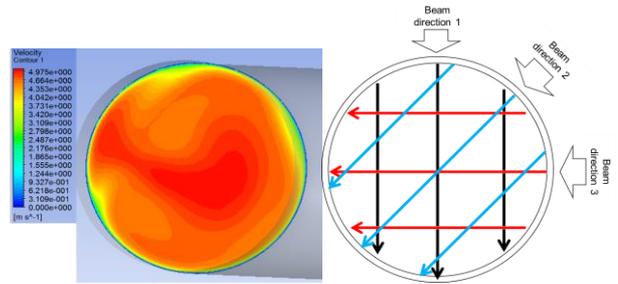


Figure 4: Velocity contours and beam directions in a pipe. The left image shows a circular velocity contour plot with a color scale from 0.000e+000 to 4.975e+000 m/s. The right image shows a schematic of a pipe cross-section with three parallel beams (Beam 1, 2, 3) and their directions indicated by arrows.

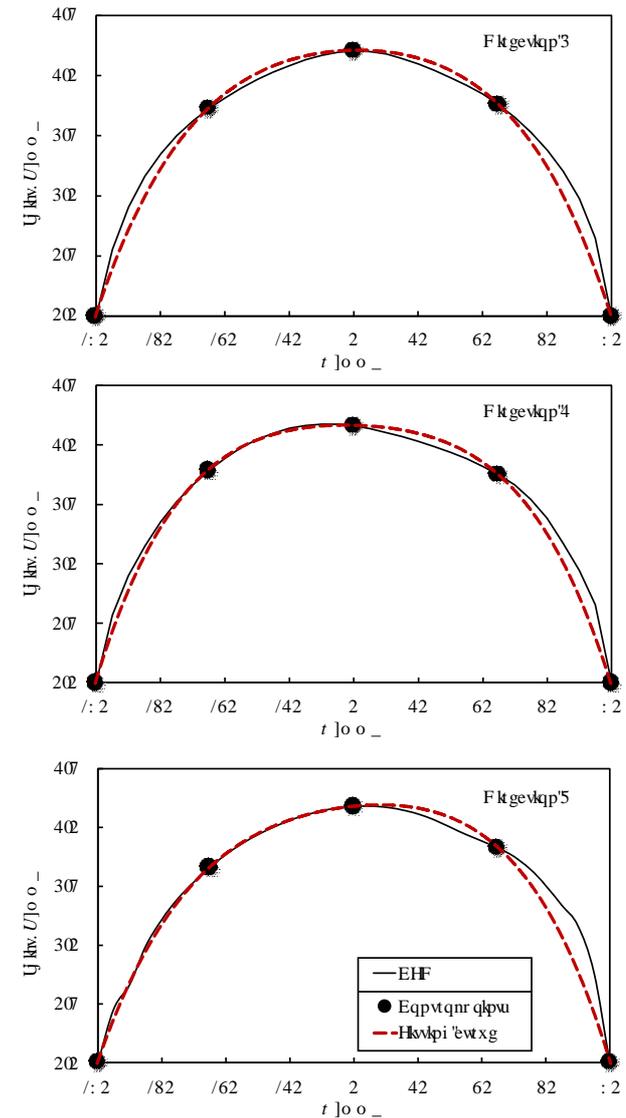
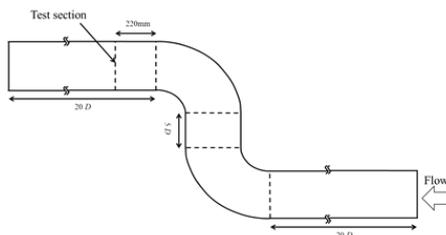


Figure 5: Velocity profiles for different flow conditions. The graphs compare EHF (solid line) with experimental data (black dots) and a theoretical model (dashed red line). The graphs are labeled Fk gevlqp3, Fk gevlqp4, and Fk gevlqp5.

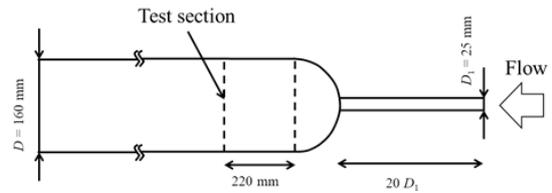
Figure 2 shows the example of the calculated velocity distribution as well as the angular alignment of the parallel 3 beams through the cross section of pipe. The inner diameter of pipe was 160 mm, distance between the end of the second bend and the test section was 220 mm. Detailed geometry of the pipes will be appeared in the following section. The  $k-\epsilon$  model was used as a turbulent model. Homogeneous inlet velocity and outlet pressure were used as the boundary conditions. Expected shift distributions in terms of the beam orientation were depicted in figure 3. The separation between parallel beams was 45 mm. Fitting with the corresponding three-point shift values as well as the  $s = 0$  at the both edges, the fitting curves show good agreement with the shift distribution obtained from the velocity distribution from the numerical simulation.

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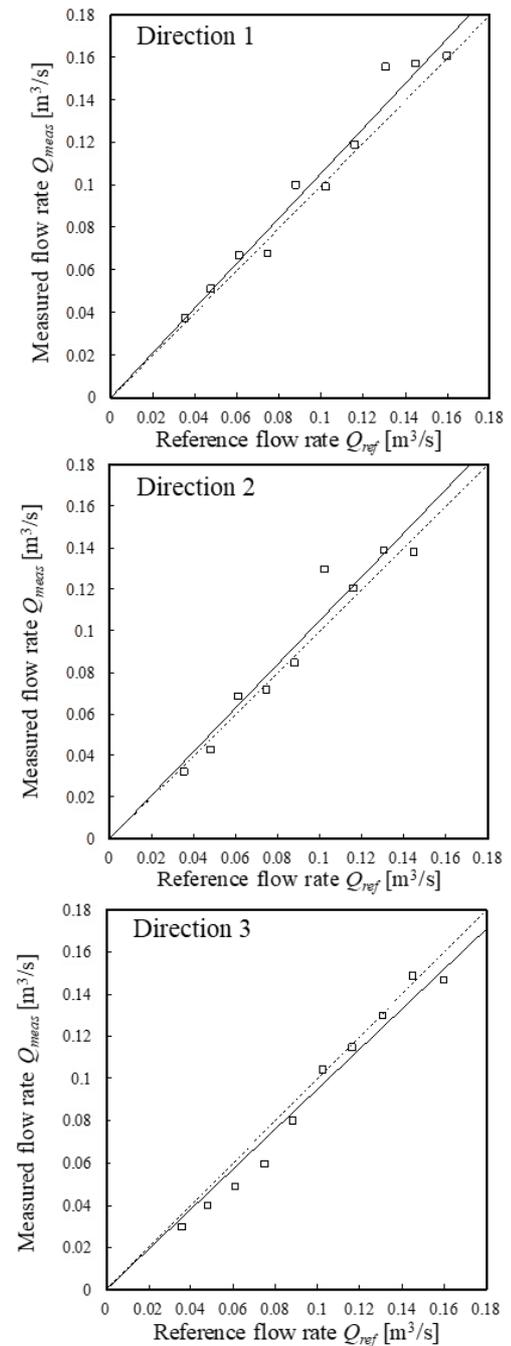
Figure 4 and figure 5 illustrate the detailed geometry of the experimental set up used in the experiments. Both diameter of pipe and dimension of bended pipe were identical to the previous numerical simulation. In both cases, the test sections were located at 220 mm from the 2nd bend or expanded section in which the conventional single path flowmeters could not be applied. A centrifugal fan was installed at the further downstream from the test section and was controlled with the variable frequency inverter with the shielded enclosure in order not to affect the electrical circuit. Frequency of the emitted ultrasound was 40 kHz, maximum voltage for the ultrasound transmitter was 20 V. The magnitude of the shift of the ultrasound intensity distribution was determined with the 3ch receiver array. Other equipment such as analog circuit, A/D convertor and signal processing software were identical to the previous study [8]. Figure 6 compares the measured flow rate by using the reference orifice flow meter and the present method. Since the angular alignment of the parallel beam will significantly affect the obtained flow rate in practical applications, the effect of the angle was evaluated. Flow rate was varied from 0 to 0.16 m<sup>3</sup>/s, which is equal to 576 m<sup>3</sup>/h. Re number was 21000. The comparisons show that the linear relation between flow rates were obtained with every angular alignment. Maximum error was 15 % in the worst case at the particular flow rate with the angular alignment of direction 2. The proposed three-parallel paths method could be applied to the flow rate measurement with the distorted velocity profile after the consecutive elbows.



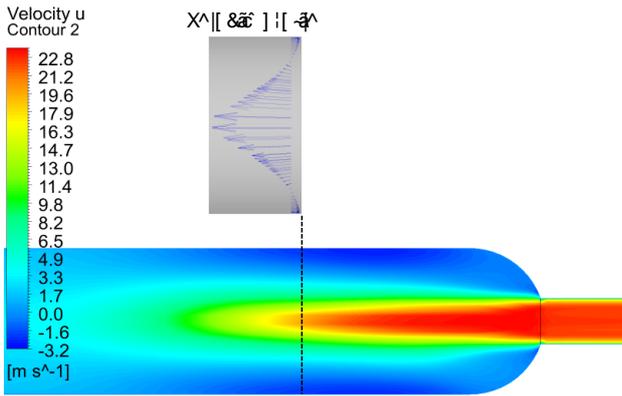
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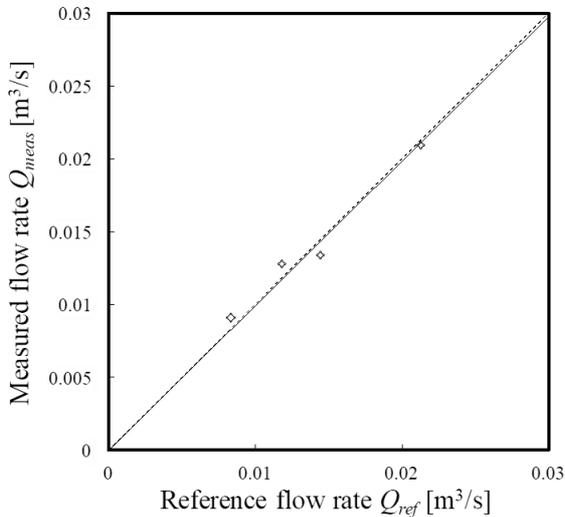
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The flow rate measurement after a pair of bended pipes as well as the expansion section was developed that employed the ultrasound shift method with parallel beams. The detailed velocity profiles after the disturbing sections were firstly calculated by a commercial CFD software. From the numerical analysis, the three-point shift measurement enables to obtain the coefficients of the fitting curve of the shift distribution and is sufficient for the determination of the volume flow rate under the present configurations. From the experiments results, it was confirmed that the measurement error of the flow rate with the consecutive double bend system was 15%, that with the expansion flow was 5 %.

## F YZf YbWwG'

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